Hydraulic gates are utilized in multiple capacities in modern society. As such, the failure of these gates can have disastrous consequences, and it is imperative to develop new methods to avoid these occurrences. Dynamic Stability of Hydraulic Gates and Engineering for Flood Prevention is a critical reference source containing scholarly research on engineering techniques and mechanisms to decrease the failure rate of hydraulic gates. Including a range of perspectives on topics such as fluid dynamics, vibration mechanisms, and flow stability, this book is ideally designed for researchers, academics, engineers, graduate students, and practitioners interested in the study of hydraulic gate structure. The four-volume set LNAI 6276–6279 constitutes the refereed proceedings of the 14th International Conference on Knowledge-Based Intelligent Information and Engineering Systems, KES 2010, held in Cardiff, UK, in September 2010. The 272 revised papers presented were carefully reviewed and selected from 360 submissions. They present the results of high-quality research on a broad range of intelligent systems topics. For researchers and practitioners, an accessible and integrated treatment of hydrodynamic control of wave energy devices. This volume contains the peer-reviewed proceedings of the International Conference on Modelling and Simulation (MS-17), held in Kolkata, India, 4th-5th November 2017, organized by the Association for the Advancement of Modelling and Simulation Techniques in Enterprises (AMSE, France) in association with the Institution of Engineering Technology (IET, UK), Kolkata Network. The contributions contained here showcase some recent advances in modelling and simulation across various aspects of science and technology. This book brings together articles describing applications of modelling and simulation techniques in fields as diverse as physics, mathematics, electrical engineering, industrial electronics, control, automation, power systems, energy and robotics. It includes a special section on mechanical, fuzzy, optical and opto-electronic control of oscillations. It provides a snapshot of the state of the art in modelling and simulation methods and their applications, and will be of interest to researchers and engineering professionals from industry, academia and research organizations. Highly regarded for its accessibility and focus on practical applications, Control Systems Engineering offers students a comprehensive introduction to the design and analysis of feedback systems that support modern technology. Going beyond theory and abstract mathematics to translate key concepts into physical control systems design, this text presents real-world case studies, challenging chapter questions, and detailed
explanations with an emphasis on computer aided design. Abundant illustrations facilitate comprehension, with over 800 photos, diagrams, graphs, and tables designed to help students visualize complex concepts. Multiple experiment formats demonstrate essential principles through hypothetical scenarios, simulations, and interactive virtual models, while Cyber Exploration Laboratory Experiments allow students to interface with actual hardware through National Instruments' myDAQ for real-world systems testing. This emphasis on practical applications has made it the most widely adopted text for core courses in mechanical, electrical, aerospace, biomedical, and chemical engineering. Now in its eighth edition, this top-selling text continues to offer in-depth exploration of up-to-date engineering practices.

At publication, The Control Handbook immediately became the definitive resource that engineers working with modern control systems required. Among its many accolades, that first edition was cited by the AAP as the Best Engineering Handbook of 1996. Now, 15 years later, William Levine has once again compiled the most comprehensive and authoritative resource on control engineering. He has fully reorganized the text to reflect the technical advances achieved since the last edition and has expanded its contents to include the multidisciplinary perspective that is making control engineering a critical component in so many fields. Now expanded from one to three volumes, The Control Handbook, Second Edition brilliantly organizes cutting-edge contributions from more than 200 leading experts representing every corner of the globe. They cover everything from basic closed-loop systems to multi-agent adaptive systems and from the control of electric motors to the control of complex networks. Progressively organized, the three volume set includes: Control System Fundamentals, Control System Applications, Control System Advanced Methods.

Any practicing engineer, student, or researcher working in fields as diverse as electronics, aeronautics, or biomedicine will find this handbook to be a time-saving resource filled with invaluable formulas, models, methods, and innovative thinking. In fact, any physicist, biologist, mathematician, or researcher in any number of fields developing or improving products and systems will find the answers and ideas they need. As with the first edition, the new edition not only stands as a record of accomplishment in control engineering but provides researchers with the means to make further advances.

The Temperature measurement of liquid in a tank can be controlled by classical and advance control algorithms applying PID, FUZZY LOGIC, SFB, LQR. Here, we consider a three tank noninteracting system. We observed that tank1 affects the dynamic behavior of tank2. Similarly, tank2 affects the dynamic behavior of tank3 and vice versa, because the flow rate F1 depends on the difference between liquid levels h1 and h2. Thus, a change in the inlet flowrate affects the liquid level in the tank, which in turn affects the temperature of the liquid. Basically, it is a thermal process. Various types of temperature sensors include RTD, T/C, and Thermistor. In this particular project the author used a mercury thermometer as sensor. Mathematical models of the three tank method give a third order equation. Each tank gives a transfer function of the first order system. They make it easy to check whether a particular algorithm is giving the requisite results. A lot of work has been carried out on the temperature control in terms of its stabilization. Many attempts have been made to control the response of temperature measuring systems. This title presents a balanced blend between classical and intelligent load frequency control techniques, which is determinant for continuous supply of power loads. The classical control techniques introduced in this book include PID, pole placement, observer-based state feedback, static and dynamic output feedback controllers while the intelligent control techniques explained here are of adaptive fuzzy control types. This book will analyze and design different decentralized LF controllers in order to maintain the frequency deviations of each power area within the limits and keep the tie-line power flow between different power areas at the scheduled levels.

This streamlined review gets you solving problems quickly to measure your readiness for the PE exam. The text provides detailed solutions to problems with pointers to references for further study if needed, as well as brief coverage of the concepts and applications covered on the exam. For busy professionals, Electrical Engineering: A Referenced Review is an ideal concise review. Book jacket. This textbook covers the essential aspects of process safety engineering in a practical and comprehensive manner. It provides readers with an understanding of process safety hazards in the refining and petrochemical industries and how to manage them in a reliable and professional manner. It covers the most important concepts: static electricity, intensity of thermal radiation, thermodynamics of fluid phase equilibria, boiling liquid expanding vapor explosion (BLEVE), emission source models, hazard identification methods, risk control and methods for achieving manufacturing excellence while also focusing on safety. Extensive case studies are included. Aimed at senior undergraduate and graduate chemical engineering students and practicing engineers, this book covers process safety principles and engineering
practice authoritatively, with comprehensive examples: • Fundamentals, methods, and procedures for the industrial practice of process safety engineering. • The thermodynamic fundamentals and computational methods for release rates from ruptures in pipelines, vessels, and relief valves. • Fundamentals of static electricity hazards and their mitigation. • Quantitative assessment of fires and explosions. • Principles of dispersion calculations for toxic or flammable gases and vapors. • Methods of qualitative and quantitative risk assessment and control. Using a practical approach that includes only necessary theoretical background, this book focuses on applied problems that motivate readers and help them understand the concepts of automatic control. The text covers servomechanisms, hydraulics, thermal control, mechanical systems, and electric circuits. It explains the modeling process, introduces the problem solution, and discusses derived results. Presented solutions are based directly on math formulas, which are provided in extensive tables throughout the text. This enables readers to develop the ability to quickly solve practical problems on control systems. System Dynamics for Engineering Students: Concepts and Applications discusses the basic concepts of engineering system dynamics. Engineering system dynamics focus on deriving mathematical models based on simplified physical representations of actual systems, such as mechanical, electrical, fluid, or thermal, and on solving the mathematical models. The resulting solution is utilized in design or analysis before producing and testing the actual system. The book discusses the main aspects of a system dynamics course for engineering students; mechanical, electrical, and fluid and thermal system modeling; the Laplace transform technique; and the transfer function approach. It also covers the state space modeling and solution approach; modeling system dynamics in the frequency domain using the sinusoidal (harmonic) transfer function; and coupled-field dynamic systems. The book is designed to be a one-semester system-dynamics text for upper-level undergraduate students with an emphasis on mechanical, aerospace, or electrical engineering. It is also useful for understanding the design and development of micro- and macro-scale structures, electric and fluidic systems with an introduction to transduction, and numerous simulations using MATLAB and SIMULINK. The first textbook to include a chapter on the important area of coupled-field systems Provides a more balanced treatment of mechanical and electrical systems, making it appealing to both engineering specialties What the experts have to say about Model-Based Testing for Embedded Systems: "This book is exactly what is needed at the exact right time in this fast-growing area. From its beginnings over 10 years ago of deriving tests from UML statecharts, model-based testing has matured into a topic with both breadth and depth. Testing embedded systems is a natural application of MBT, and this book hits the nail exactly on the head. Numerous topics are presented clearly, thoroughly, and concisely in this cutting-edge book. The authors are world-class leading experts in this area and teach us well-used and validated techniques, along with new ideas for solving hard problems. "It is rare that a book can take recent research advances and present them in a form ready for practical use, but this book accomplishes that and more. I am anxious to recommend this in my consulting and to teach a new class to my students." —Dr. Jeff Offutt, professor of software engineering, George Mason University, Fairfax, Virginia, USA "This handbook is the best resource I am aware of on the automated testing of embedded systems. It is thorough, comprehensive, and authoritative. It covers all important technical and scientific aspects but also provides highly interesting insights into the state of practice of model-based testing for embedded systems." —Dr. Lionel C. Briand, IEEE Fellow, Simula Research Laboratory, Lysaker, Norway, and professor at the University of Oslo, Norway "As model-based testing is entering the mainstream, such a comprehensive and intelligible book is a must-read for anyone looking for more information about improved testing methods for embedded systems. Illustrated with numerous aspects of these techniques from many contributors, it gives a clear picture of what the state of the art is today." —Dr. Bruno Legeard, CTO of Smartesting, professor of Software Engineering at the University of Franche-Comté, Besançon, France, and co-author of Practical Model-Based Testing The objective of this book is to provide a collection of solved problems on control systems, with an emphasis on practical problems. System functionality is described, the modeling process is explained, the problem solution is introduced, and the derived results are discussed. Each chapter ends with a discussion on applying MATLAB®, LabVIEW, and/or Comprehensive Control to the previously introduced concepts. The aim of the book is to help an average reader understand the concepts of control systems through problems and applications. The solutions are based directly on math formulas given in extensive tables throughout the text. The Industrial Electronics Handbook, Second Edition combines traditional and newer, more specialized knowledge that will help industrial electronics engineers develop practical solutions for the design
and implementation of high-power applications. Embracing the broad technological scope of the field, this collection explores fundamental areas, including analog and digital circuits, electronics, electromagnetic machines, signal processing, and industrial control and communications systems. It also facilitates the use of intelligent systems—such as neural networks, fuzzy systems, and evolutionary methods—in terms of a hierarchical structure that makes factory control and supervision more efficient by addressing the needs of all production components. Enhancing its value, this fully updated collection presents research and global trends as published in the IEEE Transactions on Industrial Electronics Journal, one of the largest and most respected publications in the field. Control and Mechatronics presents concepts of control theory in a way that makes them easily understandable and practically useful for engineers or students working with control system applications. Focusing more on practical applications than on mathematics, this book avoids typical theorems and proofs and instead uses plain language and useful examples to: Concentrate on control system analysis and design, comparing various techniques Cover estimation, observation, and identification of the objects to be controlled—to ensure accurate system models before production Explore the various aspects of robotics and mechatronics Other volumes in the set: Fundamentals of Industrial Electronics Power Electronics and Motor Drives Industrial Communication Systems Intelligent SystemsPrecise dynamic models of processes are required for many applications, ranging from control engineering to the natural sciences and economics. Frequently, such precise models cannot be derived using theoretical considerations alone. Therefore, they must be determined experimentally. This book treats the determination of dynamic models based on measurements taken at the process, which is known as system identification or process identification. Both offline and online methods are presented, i.e. methods that post-process the measured data as well as methods that provide models during the measurement. The book is theory-oriented and application-oriented and most methods covered have been used successfully in practical applications for many different processes. Illustrative examples in this book with real measured data range from hydraulic and electric actuators up to combustion engines. Real experimental data is also provided on the Springer webpage, allowing readers to gather their first experience with the methods presented in this book. Among others, the book covers the following subjects: determination of the non-parametric frequency response, (fast) Fourier transform, correlation analysis, parameter estimation with a focus on the method of Least Squares and modifications, identification of time-variant processes, identification in closed-loop, identification of continuous time processes, and subspace methods. Some methods for nonlinear system identification are also considered, such as the Extended Kalman filter and neural networks. The different methods are compared by using a real three-mass oscillator process, a model of a drive train. For many identification methods, hints for the practical implementation and application are provided. The book is intended to meet the needs of students and practicing engineers working in research and development, design and manufacturing. For senior or graduate-level students taking a first course in Control Theory (in departments of Mechanical, Electrical, Aerospace, and Chemical Engineering). A comprehensive, senior-level textbook for control engineering. Ogata's Modern Control Engineering, 5/e , offers the comprehensive coverage of continuous-time control systems that all senior students must have, including frequency response approach, root-locus approach, and state-space approach to analysis and design of control systems. The text provides a gradual development of control theory, shows how to solve all computational problems with MATLAB, and avoids highly mathematical arguments. A wealth of examples and worked problems are featured throughout the text. The new edition includes improved coverage of Root-Locus Analysis (Chapter 6) and Frequency-Response Analysis (Chapter 8). The author has also updated and revised many of the worked examples and end-of-chapter problems. This text is ideal for control systems engineers. The book consists of 21 chapters which present interesting applications implemented using the LabVIEW environment, belonging to several distinct fields such as engineering, fault diagnosis, medicine, remote access laboratory, internet communications, chemistry, physics, etc. The virtual instruments designed and implemented in LabVIEW provide the advantages of being more intuitive, of reducing the implementation time and of being portable. The audience for this book includes PhD students, researchers, engineers and professionals who are interested in finding out new tools developed using LabVIEW. Some chapters present interesting ideas and very detailed solutions which offer the immediate possibility of making fast innovations and of generating better products for the market. The effort made by all the scientists who contributed to editing this book was significant and as a result new and viable applications were presented. This textbook presents theory and practice in the context of automatic
control education. It presents the relevant theory in the first eight chapters, applying them later on to the control of several real plants. Each plant is studied following a uniform procedure: a) the plant’s function is described, b) a mathematical model is obtained, c) plant construction is explained in such a way that the reader can build his or her own plant to conduct experiments, d) experiments are conducted to determine the plant’s parameters, e) a controller is designed using the theory discussed in the first eight chapters, f) practical controller implementation is performed in such a way that the reader can build the controller in practice, and g) the experimental results are presented. Moreover, the book provides a wealth of exercises and appendices reviewing the foundations of several concepts and techniques in automatic control. The control system construction proposed is based on inexpensive, easy-to-use hardware. An explicit procedure for obtaining formulas for the oscillation condition and the oscillation frequency of electronic oscillator circuits is demonstrated as well. Carefully structured to instill practical knowledge of fundamental issues, Optical Fiber Communication Systems with MATLAB® and Simulink® Models describes the modeling of optically amplified fiber communications systems using MATLAB® and Simulink®. This lecture-based book focuses on concepts and interpretation, mathematical procedures, and engineering applications, shedding light on device behavior and dynamics through computer modeling. Supplying a deeper understanding of the current and future state of optical systems and networks, this Second Edition: Reflects the latest developments in optical fiber communications technology Includes new and updated case studies, examples, end-of-chapter problems, and MATLAB® and Simulink® models Emphasizes DSP-based coherent reception techniques essential to advancement in short- and long-term optical transmission networks Optical Fiber Communication Systems with MATLAB® and Simulink® Models, Second Edition is intended for use in university and professional training courses in the specialized field of optical communications. This text should also appeal to students of engineering and science who have already taken courses in electromagnetic theory, signal processing, and digital communications, as well as to optical engineers, designers, and practitioners in industry. This proceedings bring together contributions from researchers from academia and industry to report the latest cutting edge research made in the areas of Fuzzy Computing, Neuro Computing and hybrid Neuro-Fuzzy Computing in the paradigm of Soft Computing. The FANCCO 2015 conference explored new application areas, design novel hybrid algorithms for solving different real world application problems. After a rigorous review of the 68 submissions from all over the world, the referees panel selected 27 papers to be presented at the Conference. The accepted papers have a good, balanced mix of theory and applications. The techniques ranged from fuzzy neural networks, decision trees, spiking neural networks, self organizing feature map, support vector regression, adaptive neuro fuzzy inference system, extreme learning machine, fuzzy multi criteria decision making, machine learning, web usage mining, Takagi-Sugeno Inference system, extended Kalman filter, Goedel type logic, fuzzy formal concept analysis, biclustering etc. The applications ranged from social network analysis, twitter sentiment analysis, cross domain sentiment analysis, information security, education sector, e-learning, information management, climate studies, rainfall prediction, brain studies, bioinformatics, structural engineering, sewage water quality, movement of aerial vehicles, etc. Industrial electronics systems govern so many different functions that vary in complexity from the operation of relatively simple applications, such as electric motors, to that of more complicated machines and systems, including robots and entire fabrication processes. The Industrial Electronics Handbook, Second Edition combines traditional and new Designed for the Aeronautical/Aerospace Student or Practicing Engineer Find the material you are looking for without having to sort through unnecessary information. Intended for undergraduate and graduate students and professionals in the field of aeronautical/aerospace engineering, the Aerospace Engineering Pocket Reference is a concise, portable, go-to guide covering the entire range of information on the aerospace industry. This unique text affords readers the convenience of pocket-size portability, and presents expert knowledge on formulae and data in a way that is quickly accessible and easily understood. The convenient pocket reference includes conversion factors, unit systems, physical constants, mathematics, dynamics and mechanics of materials, fluid mechanics, thermodynamics, electrical engineering, aerodynamics, aircraft performance, propulsion, orbital mechanics, attitude determination, and attitude dynamics. It also contains appendices on chemistry, properties of materials, atmospheric data, compressible flow tables, shock wave tables, and solar system data. This authoritative text: Contains specifically tailored sections for aerospace engineering Provides key information for aerospace students Presents specificity of information (only formulae and tables) for quick and easy reference The Aerospace Engineering Pocket Reference
covers basic data as well as background information on mathematics and thermal processing, and houses more than 1000 equations and over 200 tables and figures in a single guide. This textbook on Systems and Control has been designed for 3rd-4th year course in undergraduate engineering. The emphasis has been on conceptual problems, rather than long descriptive passages. Modern methods, such as state equations, root locus, PID control, etc. have been included. Translational and rotational mechanical systems have been studied as analogies. The material is easy-to-understand, and yet builds depth-of-knowledge. The objective has been to prepare the graduating engineer for complex real-life systems and control issues. At publication, The Control Handbook immediately became the definitive resource that engineers working with modern control systems required. Among its many accolades, that first edition was cited by the AAP as the Best Engineering Handbook of 1996. Now, 15 years later, William Levine has once again compiled the most comprehensive and authoritative resource on control engineering. He has fully reorganized the text to reflect the technical advances achieved since the last edition and has expanded its contents to include the multidisciplinary perspective that is making control engineering a critical component in so many fields. Now expanded from one to three volumes, The Control Handbook, Second Edition brilliantly organizes cutting-edge contributions from more than 200 leading experts representing every corner of the globe. The first volume, Control System Fundamentals, offers an overview for those new to the field but is also of great value to those across any number of fields whose work is reliant on but not exclusively dedicated to control systems. Covering mathematical fundamentals, defining principles, and basic system approaches, this volume: Details essential background, including transforms and complex variables Includes mathematical and graphical models used for dynamical systems Covers analysis and design methods and stability testing for continuous-time systems Delves into digital control and discrete-time systems, including real-time software for implementing feedback control and programmable controllers Analyzes design methods for nonlinear systems As with the first edition, the new edition not only stands as a record of accomplishment in control engineering but provides researchers with the means to make further advances. Progressively organized, the other two volumes in the set include: Control System Applications Control System Advanced Methods Mechanical Vibration: Analysis, Uncertainties, and Control simply and comprehensively addresses the fundamental principles of vibration theory, emphasizing its application in solving practical engineering problems. The authors focus on strengthening engineers’ command of mathematics as a cornerstone for understanding vibration, control, and the ways in which uncertainties affect analysis. It provides a detailed exploration and explanation of the essential equations involved in modeling vibrating systems and shows readers how to employ MATLAB® as an advanced tool for analyzing specific problems. Forgoing the extensive and in-depth analysis of randomness and control found in more specialized texts, this straightforward, easy-to-follow volume presents the format, content, and depth of description that the authors themselves would have found useful when they first learned the subject. The authors assume that the readers have a basic knowledge of dynamics, mechanics of materials, differential equations, and some knowledge of matrix algebra. Clarifying necessary mathematics, they present formulations and explanations to convey significant details. The material is organized to afford great flexibility regarding course level, content, and usefulness in self-study for practicing engineers or as a text for graduate engineering students. This work includes example problems and explanatory figures, biographies of renowned contributors, and access to a website providing supplementary resources. These include an online MATLAB primer featuring original programs that can be used to solve complex problems and test solutions. This book develops the understanding and skills needed to be able to tackle original control problems. The general approach to a given control problem is to try the simplest tentative solution first and, when this is insufficient, to explain why and use a more sophisticated alternative to remedy the deficiency and achieve satisfactory performance. This pattern of working gives readers a full understanding of different controllers and teaches them to make an informed choice between traditional controllers and more advanced modern alternatives in meeting the needs of a particular plant. Attention is focused on the time domain, covering model-based linear and nonlinear forms of control together with robust control based on sliding modes and the use of state observers such as disturbance estimation. Feedback Control is self-contained, paying much attention to explanations of underlying concepts, with detailed mathematical derivations being employed where necessary. Ample use is made of diagrams to aid these conceptual explanations and the subject matter is enlivened by continual use of examples and problems derived from real control applications. Readers’ learning is further enhanced by experimenting with the fully-commented
MATLAB®/Simulink® simulation environment made accessible at insert URL here to produce simulations relevant to all of the topics covered in the text. A solutions manual for use by instructors adopting the book can also be downloaded from insert URL here. Feedback Control is suitable as a main textbook for graduate and final-year undergraduate courses containing control modules; knowledge of ordinary linear differential equations, Laplace transforms, transfer functions, poles and zeros, root locus and elementary frequency response analysis, and elementary feedback control is required. It is also a useful reference source on control design methods for engineers practicing in industry and for academic control researchers.

This fourth edition of the bestselling Spacecraft Systems Engineering title provides the reader with comprehensive coverage of the design of spacecraft and the implementation of space missions, across a wide spectrum of space applications and space science. The text has been thoroughly revised and updated, with each chapter authored by a recognized expert in the field. Three chapters – Ground Segment, Product Assurance and Spacecraft System Engineering – have been rewritten, and the topic of Assembly, Integration and Verification has been introduced as a new chapter, filling a gap in previous editions. This edition addresses ‘front-end system-level issues’ such as environment, mission analysis and system engineering, but also progresses to a detailed examination of subsystem elements which represents the core of spacecraft design. This includes mechanical, electrical and thermal aspects, as well as propulsion and control. This quantitative treatment is supplemented by an emphasis on the interactions between elements, which deeply influences the process of spacecraft design. Adopted on courses worldwide, Spacecraft Systems Engineering is already widely respected by students, researchers and practising engineers in the space engineering sector. It provides a valuable resource for practitioners in a wide spectrum of disciplines, including system and subsystem engineers, spacecraft equipment designers, spacecraft operators, space scientists and those involved in related sectors such as space insurance. In summary, this is an outstanding resource for aerospace engineering students, and all those involved in the technical aspects of design and engineering in the space sector.

Control Systems Engineering, now in its Fifth Edition, takes a practical approach to control systems engineering. Presenting clear and complete explanations, the text shows you how to analyze and design feedback control systems that support today’s modern technology. By working with the same physical system in each chapter, the book’s progressive case studies give you a realistic view of each stage of the control design process while a combination of qualitative and quantitative explanations provide insight into the design of parameters and system configurations. Best of all, you’ll get extensive practice in using MATLAB, Simulink, and the SISO Design Tool—industry standards that you will use in your future career. The prediction of behavior of complex systems, analysis and modeling of its structure is a vitally important problem in engineering, economy and generally in science today. Examples of such systems can be seen in the world around us (including our bodies) and of course in almost every scientific discipline including such “exotic” domains as the earth’s atmosphere, turbulent fluids, economics (exchange rate and stock markets), population growth, physics (control of plasma), information flow in social networks and its dynamics, chemistry and complex networks. To understand such complex dynamics, which often exhibit strange behavior, and to use it in research or industrial applications, it is paramount to create its models. For this purpose there exists a rich spectrum of methods, from classical such as ARMA models or Box Jenkins method to modern ones like evolutionary computation, neural networks, fuzzy logic, geometry, deterministic chaos amongst others. This proceedings book is a collection of accepted papers of the Nostradamus conference that has been held in Ostrava, Czech Republic in June 2014. This book also includes outstanding keynote lectures by distinguished guest speakers: René Lozi (France), Ponnuthurai Nagaratnam Suganthan (Singapore) and Lars Nolle (Germany). The main aim of the conference was to create a periodical possibility for students, academics and researchers to exchange their ideas and novel research methods. This conference establishes a forum for presentation and discussion of recent research trends in the area of applications of various predictive methods. The proceedings of SocProS 2015 will serve as an academic bonanza for scientists and researchers working in the field of Soft Computing. This book contains theoretical as well as practical aspects using fuzzy logic, neural networks, evolutionary algorithms, swarm intelligence algorithms, etc., with many applications under the umbrella of ‘Soft Computing’.

The book will be beneficial for young as well as experienced researchers dealing across complex and intricate real world problems for which finding a solution by traditional methods is a difficult task. The different application areas covered in the proceedings are: Image Processing, Cryptanalysis, Industrial Optimization, Supply Chain Management, Newly Proposed Nature Inspired Algorithms,